

Contents

Abstract	page
Acknowledgements	i
Contents	iii
List of Figures	v
List of Tables	vii
List of Symbols	ix
List of Abbreviations	xi
Chapter 1: Introduction	1
1.1 Introduction	1
1.2 Characterization and Selection of Driver Nodes	4
1.2.1 Techniques to Find Minimum Number of Driver Nodes	4
1.2.2 Techniques for Selecting Set of Driver Nodes	8
1.3 Motivation	11
1.4 Thesis Contributions	12
1.5 Organization of the Thesis	12
1.6 Publications	13
Chapter 2: Preliminary Concepts and Modeling of Complex Networks	15
2.1 Basic Definitions	15
2.1.1 Representation of Graphs as Matrices	16
2.2 Dynamics of Complex Networks	18
2.2.1 Control of Complex Networks	18
2.2.2 Controllability and Observability Indices	20
2.2.3 Modeling of Networks With Actuator Saturation	21
2.3 Frequency Domain Analysis of Complex Networks	22
2.4 Sensitivity Analysis of Complex Networks	23
2.4.1 Stability, Robustness and Performance Measure	24
2.4.2 Disturbance Rejection for Networked Systems	24
2.4.3 Bode's Integral Formula	24
2.5 Modeling of Power Networks	25
2.6 Summary	27
Chapter 3: Input-Output Dynamic Properties of Complex Networks	29
3.1 Introduction	29
3.2 Preliminaries	30
3.2.1 System Model and Preliminaries	30
3.3 Influence of Input-Output Dynamic Properties on Control Indices	34
3.3.1 Gain Factor of Networked Systems	34
3.3.2 DC-Gain of Peripheral Nodes	36
3.3.3 Network Zeros Based on Graph-Theoretic Approach	40
3.4 Numerical Examples	43
3.5 Summary	45
Chapter 4: Robustness of Complex Networks Based on Minimum Sensitivity	47
4.1 Introduction	47
4.2 Preliminaries	47
4.3 Effect of Network Structure on Sensitivity	49
4.3.1 Effect of Gain Factor on Sensitivity	49
4.3.2 Effect of Distance on Sensitivity	50
4.4 Simulation Results and Discussion	51
4.5 Application to Power Networks	57
4.5.1 Modeling of Power Networks	57
4.6 Summary	62
Chapter 5: Selection of Driver Nodes in Continuous-Time Complex Networks Based on Region of Attraction	63
5.1 Introduction	63

5.2	Modeling of Complex Networks With Saturated Actuators	63
5.3	Selection of Optimal Driver Nodes	66
5.3.1	<i>Problem Setup</i>	66
5.3.2	<i>Region of Attraction and Selection of Optimal Set of Driver Nodes of Anti-Stable Networked Systems With Saturated Actuators</i>	66
5.3.3	<i>Region of Attraction and Selection of Optimal Set of Driver Nodes of Unstable Networked Systems With Saturated Actuators</i>	69
5.3.4	<i>Computational Aspects for Large Complex Networks</i>	73
5.4	Simulation Results and Discussion	73
5.5	Application to Robot Formation Control	79
5.6	Summary	83
Chapter 6: Selection of Driver Nodes in Discrete-Time Complex Networks Based on Region of Attraction		85
6.1	Introduction	85
6.2	Modeling of Discrete-Time Complex Networks With Saturated Actuators	85
6.3	Selection of Optimal Driver Nodes	87
6.3.1	<i>Problem Setup</i>	87
6.3.2	<i>Region of Attraction and Selection of Optimal Set of Driver Nodes of Discrete-Time Anti-Stable Networked Systems With Saturated Actuators</i>	87
6.3.3	<i>Region of Attraction and Selection of Optimal Set of Driver Nodes of Discrete-Time Unstable Networked Systems With Saturated Actuators</i>	90
6.4	Simulation Results and Discussion	94
6.5	Summary	98
Chapter 7: Conclusions and Future Work		101
7.1	Conclusions	101
7.2	Recommendations for Future Work	102
References		103